

3 & 4 Finger Jaw

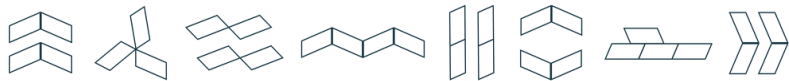
For SAAB Seaeye eM1-7 Electrical Manipulator



**Test proven
by SAAB**

The 3 & 4 finger manipulator jaw is intended as an electrically operated tool. The front adapter assembly comes complete with the center pivot pin and all necessary parts, and will replace the standard parallel grip by loosening 4 bolts and the center bolt.

The 1-Finger Claw can easily be replaced with the Wide 2-Finger Claw, changing it from a 3-finger jaw to a 4-finger jaw.



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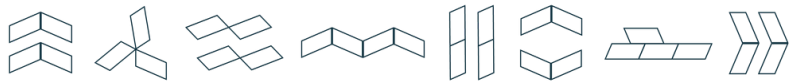


Key Functional Features

- Wide opening jaws to 182 mm with serrated fingers for firm reliable grip
- Simple and reliable design
- Standard interface designed for Saab Seaeye eM1-7 electrical Manipulator
- Finger Claws same type as for the Schilling Robotics manipulator arm
- Supplied with Imenco OEM documentation
- Supplied with tailor made transport and - storage case
- Depth rating 4000 MSW
- Main parts: EN 1.4418 Material
- Special Claw Designs Available on request

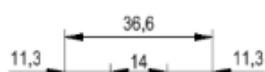
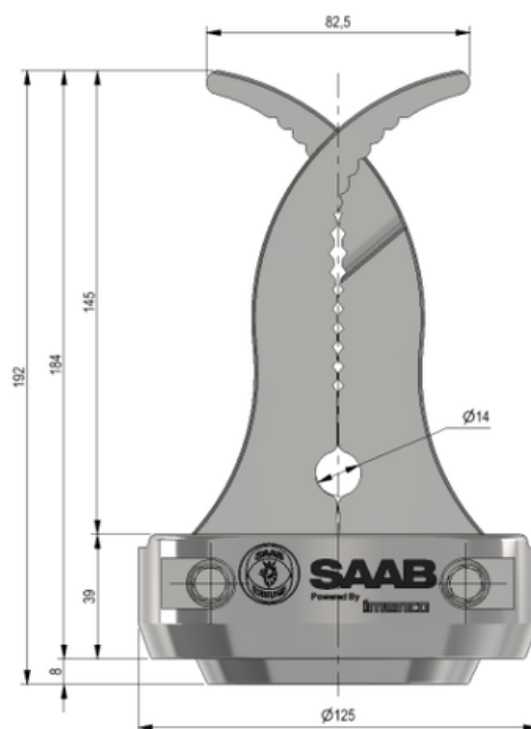
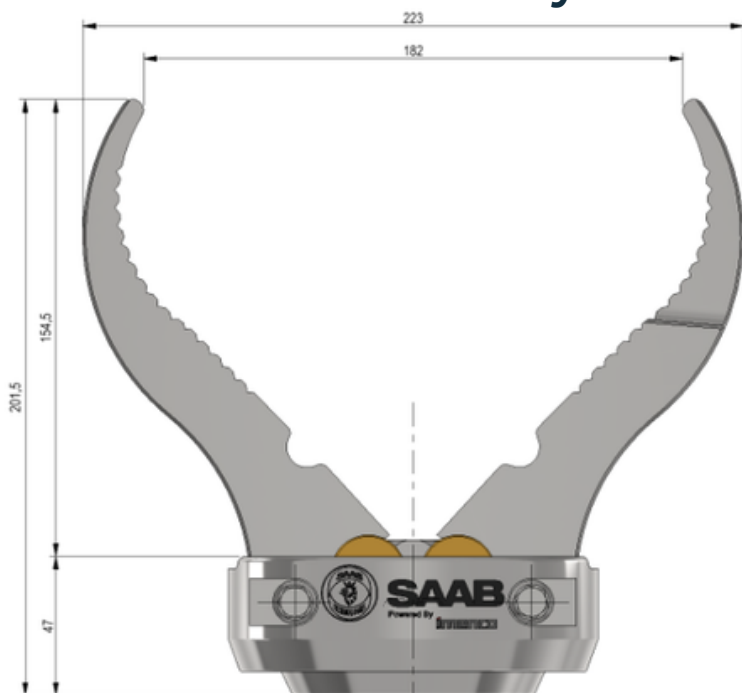
Technical Characteristics	Model Values
Tailor Made Case	L=420 B=330 H=180 mm
Claw Assy Weight (dry)	3-Finger 4,6 Kg / 4-Finger: 5,5 Kg
Claw Assy Weight (submerged)	3-Finger: 4 Kg / 4-Finger: 4,8 Kg
Temperature Range	-20 / +40 °C

For further information, email
commercial@imenco.com

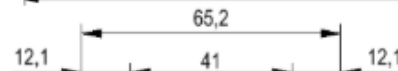
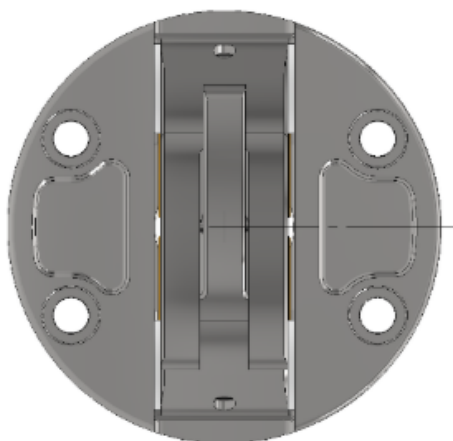


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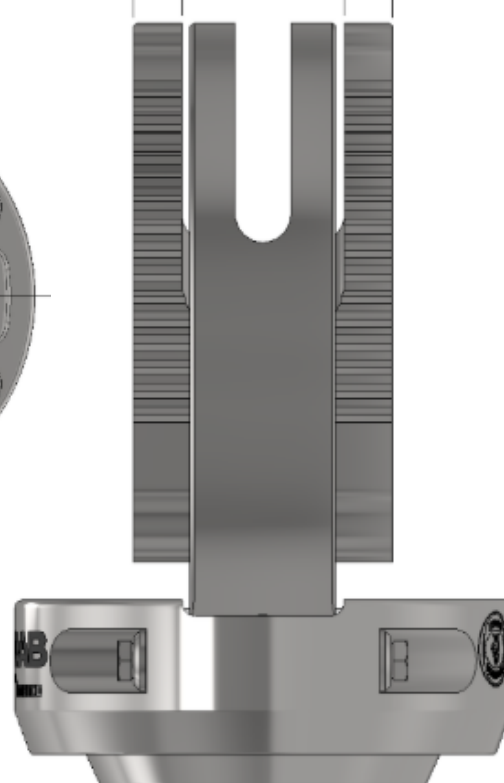
Key dimensions



Top view



3-Finger claw



4-Finger claw